





## Article

# Unbalanced Voltage Compensation with Optimal Voltage Controlled Regulators and Load Ratio Control Transformer

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**Abstract:** Penetration of equipment such as photovoltaic power generations (PV), heat pump water heaters (HP), and electric vehicles (EV) introduces voltage unbalance issues in distribution systems. Controlling PV and energy storage system (ESS) outputs or coordinated EV charging are investigated for voltage unbalance compensation. However, some issues exist, such as dependency on installed capacity and fairness among consumers. Therefore, the ideal way to mitigate unbalanced voltages is to use grid-side equipment mainly. This paper proposes a voltage unbalance compensation based on optimal tap operation scheduling of three-phase individual controlled step voltage regulators (3 $\phi$ SVR) and load ratio control transformer (LRT). In the formulation of the optimization problem, multiple voltage unbalance metrics are comprehensively included. In addition, voltage deviations, network losses, and coordinated tap operations, which are typical issues in distribution systems, are considered. In order to investigate the mutual influence among voltage unbalance and other typical issues, various optimization problems are formulated, and then they are compared by numerical simulations. The results show that the proper operation of 3 $\phi$ SVRs and LRT effectively mitigates voltage unbalance. Furthermore, the results also show that voltage unbalances and other typical issues can be improved simultaneously with appropriate formulations.

**Keywords:** distribution system; load ratio control transformer; optimal scheduling; step voltage regulator; voltage unbalance

## 1. Introduction

The growing global momentum toward decarbonization leads to the increasing use of photovoltaic power generation (PV), heat pump water heater (HP), and electric vehicles (EV). However, the variability of generation and load of such equipment introduces voltage unbalance issues in low voltage (LV) and medium voltage (MV) distribution systems. In [1], voltage unbalance is reported by monitoring an actual LV distribution system. Authors in [2] explained HPs' and EVs' random behavior, non-uniformed single-phase loads, and network asymmetry causes voltage unbalance. Stochastic investigations of the relationship between PV penetration and voltage unbalance are conducted in [3,4]; it reported that unacceptable voltage unbalance can occur depending on the PV penetration and placement. In [5,6], uncoordinated charging of EVs adversely affects voltage

balances are showed. The increase in voltage unbalances lead to induction motor failures, increased losses, and additional cost of increasing a particular phase of the distribution line capacity. Therefore, in modern distribution systems with penetration of variable loads and distributed power sources, it is necessary to consider voltage unbalance compensation.

Conventionally, voltage regulation in distribution systems is performed using tap control of a load ratio control transformer (LRT) in distribution substations and step voltage regulators (SVR) installed on lines. The three-phase simultaneously tap operation of these devices keeps the voltage magnitude within the appropriate range, but they cannot mitigate voltage unbalance. Using a static var compensator (SVC) is an effective means, but its drawback is the high cost of equipment.

Different solutions are proposed in the literature to regulate unbalanced voltage in distribution systems. In [7], voltage deviation and the number of tap operations are minimized by optimizing reactive power injection of PV inverter and tap operations of on-load tap changer (OLTC). Authors in [8] proposed a capacitor placement method based on genetic algorithm (GA) to minimize the losses with appropriate voltage profiles. In [9], a modified firefly algorithm solved the optimal placement and capacity of distributed power sources for loss minimization. Distributed power sources allocation using a particle swarm optimization (PSO) based approach is presented in [10]. However, these studies evaluate voltage profiles only by the voltage deviations and do not consider the voltage unbalance metrics.

In order to evaluate voltage unbalance, various organizations such as IEC [11], IEEE [12], and NEMA [13] define different voltage unbalance metrics. Several papers use these metrics to assess voltage unbalance and thereby reduce voltage unbalance. In [3], voltage unbalances reduced by controlling the reactive power of the PV inverter. Authors in [5] minimized voltage unbalances by optimizing the plugin electric vehicles (PEV) charging with GA. Optimal scheduling of microgrid distributed resources for minimizing voltage unbalance is proposed in [14].

The authors of [3,5,14] focused on only one voltage unbalance metric. However, A few papers show that the consideration of only one voltage unbalance metric is insufficient to compensate for voltage unbalances. Authors in [15] reported that minimizing one voltage unbalance definition might increase another voltage unbalance definition. The condition where IEC definition is zero but unbalances remains is shown in [16]. Moreover, the IEEE definition does not include information on the voltage angle; obviously, it is impossible to detect unbalanced conditions completely.

Voltage unbalance compensation considering multiple voltage unbalance metrics is proposed in [15–17]. Authors in [15] provided voltage unbalance compensation by reactive power control of PV inverters based on IEC, IEEE, and NEMA definitions. In [16], in addition to the IEC definition,  $VUF_0$  and  $MVUF$  are additionally defined, and voltage unbalance compensation with active and reactive power control of smart inverters is proposed. Voltage management by demand response and individual phase control of substation OLTC considering the IEC definition and  $VUF_0$  is presented in [17].

Voltage regulation of unbalanced systems based on sensitivity analysis or controllers is investigated in [18–20]. These controller-based methods are beneficial in low computational cost, easy implementation, and decentralized control during a communication network failure. However, for unbalance metrics such as IEC and NEMA definitions, which contain information on voltage angle, the relationship between voltage value and metrics is complicated. Consequently, it is not easy to apply the controller-based method. Authors in [18] proposed a sensitivity-based voltage control with variously connected substation voltage regulators, but only the voltage deviations are monitored. The individual phase tap control of OLTC based on proportional control proposed in [19] instead increases the voltage unbalance. In [20], the sensitivity-based individual phase reactive power control of energy storage system (ESS) improves voltage magnitude unbalance defined by IEEE, but it is not easy to extend it to consider voltage angle unbalance. Hence, an optimization-based approach is suitable for voltage regulation considering multiple voltage unbalance metrics.

Furthermore, most of the existing approaches (e.g., [3,5,15,16,20]) use end-user equipment such as PV inverters, EVs, capacitors, and ESS. Hence, the methods introduce some issues such as dependency on the equipment's capacity, and incentives or fairness to control owners' equipment. Therefore, it is not practical to depend only on these methods for unbalance compensation, and it is desirable to voltage unbalance compensation using grid-side equipment mainly.

This paper investigates voltage unbalance compensation by optimal tap operation scheduling of three-phase individual controlled SVRs ( $3\phi$ SVR) composed of three single-phase regulators and LRT. The  $3\phi$ SVRs can provide voltage unbalance compensation, and the LRT can provide control margins to the  $3\phi$ SVRs by compensating overall voltage drops. A tabu search-based heuristic algorithm and a penalty approach formulation are implemented. In the formulation of the optimization problem, multiple voltage unbalance metrics are comprehensively considered. In addition, voltage deviations, network losses, and coordinated tap operations, which are typical issues in distribution systems, are also considered. Various optimization problems are formulated to investigate the impact of considering the typical issues on unbalance compensation. A typical MV three-phase distribution system with assuming PV penetration and unbalanced load is used to simulate daily tap operation.

In summary, the significant contributions of this paper are:

1. The effectiveness validation of voltage unbalance compensation using  $3\phi$ SVRs and LRT.
2. Comprehensive integration of multiple unbalance metrics into the optimization problem to address different voltage unbalance definition issues.
3. Consideration of voltage deviation, network losses, and coordinated tap operation with the voltage unbalance compensation and investigation of the impact of considering these typical issues on unbalance compensation.
4. Application and implementation of tabu search-based heuristic to voltage unbalance compensation.

The rest of this paper is structured as follows: Section 2 describes the voltage unbalance metrics and other issues of unbalanced distribution systems treated in this study. In Section 3, we formulate various optimization problems. Section 4 introduces the tabu search as a solution method for optimization problems and then investigates the impact of the different formulations by comparing the solutions of optimization problems. Finally, Section 5 concludes this paper.

## 2. Voltage Unbalance Metrics and Typical Issues in Unbalanced Distribution Systems Operation

This section introduces the voltage unbalance metrics used in this study and other typical issues that a distribution system operator (DSO) must manage. In addition to voltage unbalance, voltage deviation, network losses, and coordinated tap operation will be outlined as challenges for efficient network operation.

### 2.1. Voltage Unbalance Metrics

Voltage unbalance is a condition in three-phase systems when either the phase voltages have different magnitudes, and the phase angle displacement is not equal to  $120^\circ$ , or both. Unbalanced load distribution and the penetration of single-phase PVs can increase voltage unbalance. Since there are various definitions of metrics for detecting voltage unbalance, careful attention should be paid to selecting voltage unbalance metrics. In the following subsections, the voltage unbalance metrics adopted in this study are described.

#### 2.1.1. VUF (IEC Definition)

Voltage unbalance factor (VUF) is described by the symmetrical components' negative and positive phase voltage magnitudes. The definition of VUF is provided by IEC

standard [11] and also referred to as the “true” definition. It is widely used as a primary voltage unbalance metric. It is given by

$$\begin{aligned} \text{VUF} (\%) &= \frac{|\dot{V}_2|}{|\dot{V}_1|} \times 100, \text{ where} \\ \dot{V}_1 &= \frac{\dot{V}_a + \alpha \dot{V}_b + \alpha^2 \dot{V}_c}{3}, \quad \dot{V}_2 = \frac{\dot{V}_a + \alpha^2 \dot{V}_b + \alpha \dot{V}_c}{3}. \end{aligned} \quad (1)$$

Here,  $\dot{V}_2$  and  $\dot{V}_1$  are the negative and positive phase voltage phasors, respectively;  $\dot{V}_a$ ,  $\dot{V}_b$ ,  $\dot{V}_c$  are three-phase line-to-ground voltage phasors, and  $\alpha = 1 \angle 120^\circ$ . The IEC standard requires VUF should be less than 2% in LV and MV systems.

### 2.1.2. VUF<sub>0</sub>

In few papers, VUF<sub>0</sub> is defined additionally, which is described by the symmetrical components' zero and positive phase voltage magnitudes [16,17]. Because the balanced three-phase voltage is equivalent to both the negative-phase voltage and zero-phase voltage is zero, introducing this definition is reasonable. It is given by

$$\begin{aligned} \text{VUF}_0 (\%) &= \frac{|\dot{V}_0|}{|\dot{V}_1|} \times 100, \\ \text{where } \dot{V}_0 &= \frac{\dot{V}_a + \dot{V}_b + \dot{V}_c}{3}. \end{aligned} \quad (2)$$

Here,  $\dot{V}_0$  is the zero-phase voltage phasor. VUF<sub>0</sub> is used as an unbalance metric to complement VUF. It is assumed that VUF<sub>0</sub> is required to be less than 2%. VUF and VUF<sub>0</sub> detect angle and magnitude unbalances; the NEMA [13] definition also detects angle and magnitude unbalances, but since VUF and VUF<sub>0</sub> sufficiently detect these, the NEMA definition is omitted in this paper.

### 2.1.3. PVUR (IEEE Definition)

The unbalance metric defined by IEEE [12] is referred to as phase voltage unbalance rate (PVUR). It is calculated using the line-to-ground phase voltage magnitudes  $V_a$ ,  $V_b$ , and  $V_c$ :

$$\begin{aligned} \text{PVUR} (\%) &= \frac{V_{\text{md}}}{V_{\text{ave}}} \times 100, \\ \text{where } V_{\text{ave}} &= \frac{V_a + V_b + V_c}{3}, \\ V_{\text{md}} &= \max\{|V_a - V_{\text{ave}}|, |V_b - V_{\text{ave}}|, |V_c - V_{\text{ave}}|\}. \end{aligned} \quad (3)$$

Since VUF and VUF<sub>0</sub> contain information on both voltage magnitude unbalances and angle unbalances, voltage magnitude unbalances cannot be monitored independently. Therefore, PVUR is used to monitor voltage magnitude unbalances independently; IEEE standard [12] prescribes that PVUR should be limited to 2% or less.

## 2.2. Voltage Deviations

Maintaining the bus voltages at a specified value is an essential requirement of power distribution systems. However, maintaining the voltages becomes more challenging in unbalanced systems due to unbalanced loads and PV installations. In order to quantify the voltage deviation of each phase, the voltage deviation rate is calculated as

$$\text{VD}_{tkn} (\%) = \frac{|V_{tkn} - V_s|}{V_s} \times 100, \quad (4)$$

where  $\text{VD}_{tkn}$  is the voltage deviation rate of the  $n$ -phase voltage at time  $t$  and bus  $k$ ,  $V_{tkn}$  is the  $n$ -phase voltage at time  $t$  and bus  $k$ , and  $V_s$  is the reference voltage. For the reliable

operation of the distribution system, the voltage deviation rate must be less than the specified value. Therefore, all bus voltages should be constraints as

$$VD_{tkn} \leq VD_{lim}, \quad (5)$$

where  $VD_{lim}$  is the constraint value of the voltage deviation rate. In general,  $VD_{tkn}$  should be limited within 10%.

### 2.3. Network Losses

Network losses are directly increasing costs. Therefore, the minimization of network losses is an important objective for efficient distribution system operations. Network loss of a particular line can be calculated as

$$Loss_{ti} = P(\dot{V}_{ti}, \dot{I}_{ti}), \quad (6)$$

where  $Loss_{ti}$  is the network loss of line  $i$  at time  $t$ ,  $\dot{V}_{ti}$  is the voltage drop of line  $i$  at time  $t$ ,  $\dot{I}_{ti}$  is the current passing through line  $i$  at time  $t$ .

### 2.4. Coordinated Operation of Control Devices

In operating multiple voltage control devices, proper coordination among them is important. In this study, the following two issues related to the coordination of tap devices, such as  $3\phi$ SVRs and LRT, are considered.

#### 2.4.1. Unbalanced Operation of Control Devices

In multiple tap control devices operation, only some of the devices may operate unevenly. When a device reaches its tap limit due to unbalanced operation, it decreases the voltage margin for sudden fluctuations in load and generation. In addition, the unbalanced operation can also make it difficult to estimate the life of the devices. In three-phase individual control, this issue is even more pronounced. Therefore, the fair sharing of control responsibilities through mutual coordination among devices is required.

#### 2.4.2. Deterioration of Control Devices

The lifetime of tap control devices is proportional to the number of tap operations. Therefore, in optimal operation to improve power quality, over-control of taps may decrease the lifetime of the devices. In general, the number of tap operations per day is limited within a specified value to avoid over-control of taps.

## 3. Optimization Problem Formulation

This section describes various optimization problems formulated to address voltage unbalances and other typical issues that a DSO interest in solving. Optimal scheduling problems for  $3\phi$ SVR and LRT are formulated as nonlinear integer optimization problems. Tap positions of the control devices are control variables. First, we explain all objective functions, penalty constraints, and constraints formulated in this paper, and then the various optimization problems formulated by the combination of these formulas are described.

### 3.1. Objective Functions

#### 3.1.1. Objective Function for Minimize VUF

For minimization of VUF only, an objective function is given by

$$f_{vuf} = \sum_{t=1}^{N_{time}} \sum_{k=1}^{N_{bus}} VUF_{tk}, \quad (7)$$

where  $VUF_{tk}$  is the VUF value of bus  $k$  at time  $t$ ,  $N_{time}$  is the total value of time intervals, and  $N_{bus}$  is the total value of buses in a system.

### 3.1.2. Objective Function for Minimize Sum of All Voltage Unbalance Metrics

The sum of all voltage unbalance metrics is minimized by

$$f_{vu} = \sum_{t=1}^{N_{time}} \sum_{k=1}^{N_{bus}} (VUF_{tk} + VUF_{0,tk} + PVUR_{tk}), \quad (8)$$

where  $VUF_{0,tk}$ ,  $PVUR_{tk}$  are the  $VUF_0$  and  $PVUR$  values of bus  $k$  at time  $t$ , respectively.

### 3.1.3. Objective Function for Minimize Loss

An objective function for minimizing network losses is given by

$$f_{loss} = \sum_{t=1}^{N_{time}} \sum_{i=1}^{N_{line}} Loss_{ti}, \quad (9)$$

where,  $Loss_{ti}$  is the network loss of line  $i$  at time  $t$ , and  $N_{line}$  is the total number of lines in a system.

## 3.2. Penalty Constraints

Most of the problems described in Section 2 are treated as penalty constraints. Penalty constraints are incorporated into the optimization problem by summation with an objective function.

### 3.2.1. Penalty Constraint to Limit Voltage Deviation Rate

A penalty constraint to limit the voltage deviation rate to within a specified value is given by

$$\text{Penalty}_{vd} = \sum_{t=1}^{N_{time}} \sum_{k=1}^{N_{bus}} \sum_{n \in a,b,c} w_{vd} d_{tkn},$$

$$\text{where } d_{tkn} = \begin{cases} 0 & \text{if } VD_{tkn} \leq VD_{lim} \\ \frac{VD_{tkn}}{VD_{lim}} & \text{otherwise} \end{cases}. \quad (10)$$

Here,  $w_{vd}$  is the weight factor for voltage deviation rate.

### 3.2.2. Penalty Constraint to Limit Voltage Unbalance Metrics

All voltage unbalance metrics is penalized as

$$\text{Penalty}_{vu} = \sum_{t=1}^{N_{time}} \sum_{k=1}^{N_{bus}} w_{vu} (u_{1,tk} + u_{2,tk} + u_{3,tk}),$$

where

$$u_{1,tk} = \begin{cases} 0 & \text{if } VUF_{tk} < VUF_{lim} \\ \frac{VUF_{tk}}{VUF_{lim}} & \text{otherwise} \end{cases},$$

$$u_{2,tk} = \begin{cases} 0 & \text{if } VUF_{0,tk} < VUF_{0,lim} \\ \frac{VUF_{0,tk}}{VUF_{0,lim}} & \text{otherwise} \end{cases},$$

$$u_{3,tk} = \begin{cases} 0 & \text{if } PVUR_{tk} < PVUR_{lim} \\ \frac{PVUR_{tk}}{PVUR_{lim}} & \text{otherwise} \end{cases}. \quad (11)$$

Here,  $VUF_{lim}$ ,  $VUF_{0,lim}$ , and  $PVUR_{lim}$  are the constraint values of the  $VUF$ ,  $VUF_0$ , and  $PVUR$ , respectively;  $w_{vu}$  is the weight factor for voltage unbalance.

### 3.2.3. Penalty Constraint to Reduce Unbalanced Operation

A following penalty constraint mitigates unbalanced tap operations:

$$\text{Penalty}_{\text{tap1}} = \sum_{t=1}^{N_{\text{time}}} \sum_{j=1}^{N_{\text{tap}}} \left( \frac{|T_{tj} - T_c|^3}{w_{\text{tap1},j}} \right), \quad (12)$$

where  $N_{\text{tap}}$  is the total number of tap control devices (each phase tap of  $3\phi$ SVRs is accounted for separately),  $T_{tj}$  is the tap position of tap device  $j$  at time  $t$ ,  $T_c$  is the tap center position, and  $w_{\text{tap1},j}$  is the weight factor for the operation of the tap control device  $j$ .

### 3.2.4. Penalty Constraint to Limit the Number of Tap Operations per Day

The number of tap operations per day is limited by following penalty constraint as

$$\text{Penalty}_{\text{tap2}} = \sum_{j=1}^{N_{\text{tap}}} w_{\text{tap2}} p_j,$$

$$\text{where } p_j = \begin{cases} 0 & \text{if } \sum_{t=1}^{N_{\text{time}}-1} \Delta T_{tj} \leq T_{\text{lim}} \\ \sum_{t=1}^{N_{\text{time}}-1} \Delta T_{tj} & \text{otherwise} \end{cases},$$

$$\Delta T_{tj} = |T_{t+1,j} - T_{tj}|. \quad (13)$$

Here,  $T_{\text{lim}}$  is the constraint value of the number of tap operations per day,  $w_{\text{tap2}}$  is the weight factor for the number of tap operations per day, and  $\Delta T_{tj}$  is the difference of the tap position between time  $t - t + 1$  of device  $j$ .

## 3.3. Constraint

### Inequality Constraint to Limit Tap Control Range

Most of the constraints were formulated as penalty constraints. The control range of the taps is formulated as a constraint. It is given by

$$T_{\min} \leq T_{tj} \leq T_{\max}, \quad (14)$$

where  $T_{\min}$  and  $T_{\max}$  are the minimum and maximum tap positions, respectively.

## 3.4. Optimal Scheduling Problem Formulation

In this subsection, we describe the formulations of five optimization problems using the objective functions, penalty constraints, and constraint introduced in the previous subsections.

### 3.4.1. Minimize VUF

The first problem formulation minimizes the VUF. It is considered in most of the existing literature. It includes the penalty constraint to limit voltage deviation rate and constraint to limit tap control range.

$$\begin{aligned} & \min \text{Objective Function (7)} \\ & \text{subject to} \\ & \text{Penalty Constraint (10)} \\ & \text{Constraint (14)} \end{aligned}$$



### 3.4.2. Minimize Sum of All Voltage Unbalance Metrics

The second problem formulation minimizes the sum of all voltage unbalance metrics. It includes the penalty constraint to limit voltage deviation rate and constraint to limit tap control range.

min Objective Function (8)  
 subject to  
 Penalty Constraint (10)  
 Constraint (14)

### 3.4.3. Minimize Losses

The third problem formulation minimizes the network losses. It includes the penalty constraint to limit voltage deviation rate and constraint to limit tap control range.

min Objective Function (9)  
 subject to  
 Penalty Constraint (10)  
 Constraint (14)

### 3.4.4. Minimize Losses with Voltage Unbalance Penalty

The fourth problem formulation minimizes the network losses with the penalty constraint to limit voltage unbalance metrics. It also includes the penalty constraint to limit voltage deviation rate and constraint to limit tap control range.

min Objective Function (9)  
 subject to  
 Penalty Constraints (10), (11)  
 Constraint (14)

### 3.4.5. Minimize Losses with Voltage Unbalance and Tap Operation Penalty

The last problem formulation minimizes the network losses with the penalty constraint to limit voltage unbalance metrics and penalty constraints for improve tap operation. It also includes the penalty constraint to limit voltage deviation rate and constraint to limit tap control range.

min Objective Function (9)  
 subject to  
 Penalty Constraints (10) – (13)  
 Constraint (14)

## 4. Simulation Results

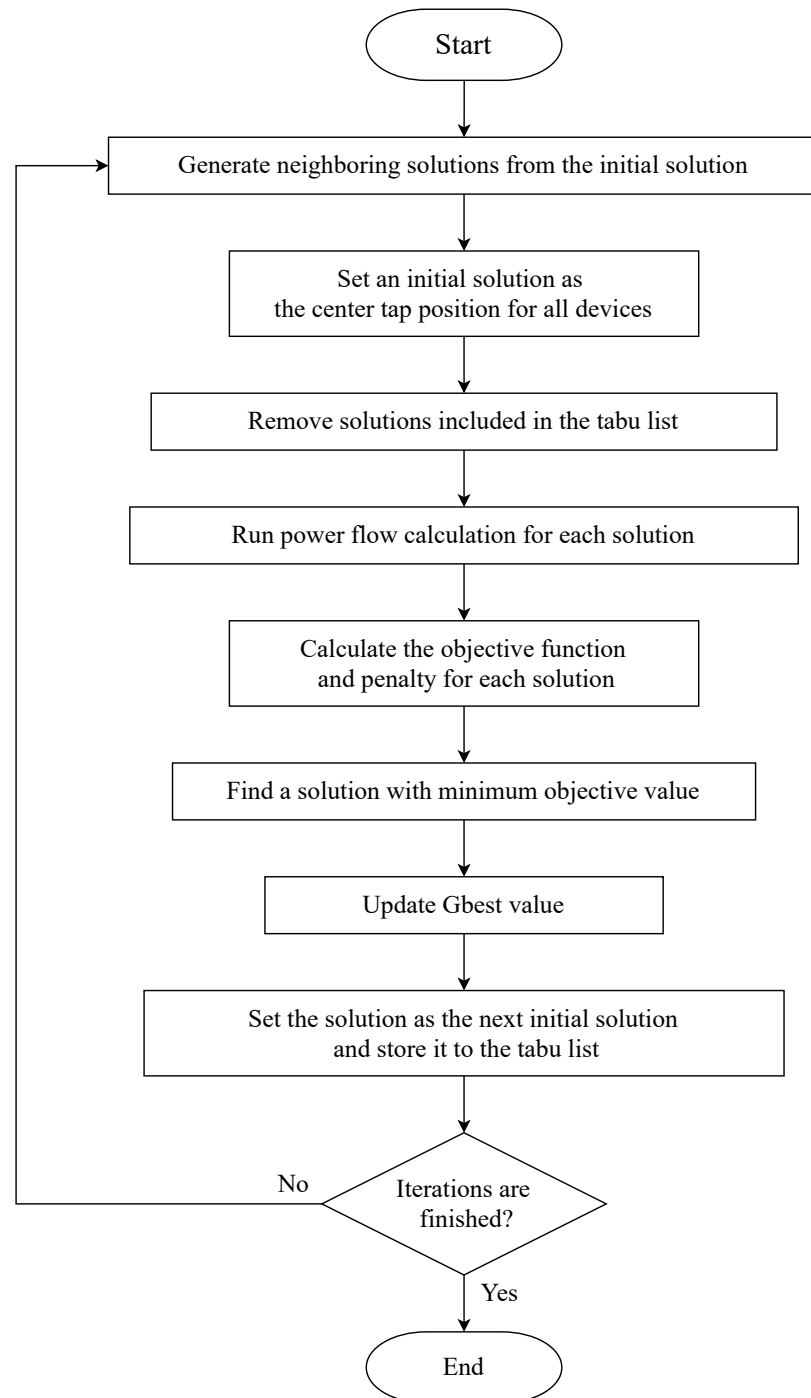
### 4.1. Optimization Method

As the solution to the nonlinear integer optimization problems, tabu search [21], a meta-heuristic algorithm based on the local search method, is applied. The tabu search is adopted because it can directly handle integer variables and is easy to apply even if the relationship between the control variables and the objective function is complex. In addition, the algorithm is deterministic, which makes it easy to implement and adjust parameters.

The basic algorithm of the tabu search is to search multiple neighborhoods of the initial solution and transition to the neighboring solution with the highest evaluation among them. Then, the solution is stored in the taboo list. While the solution is stored in the taboo list, the transition to that solution is prohibited. This prevents the solution from being looped. In addition, when the solution is not stored in the taboo list, transitions are made even when the solution deteriorates, thereby preventing the search from stagnating in local solutions.



Solutions are evaluated through power flow calculation using the backward forward sweep (BFS) method. It is performed for all neighboring solutions at each iteration. For the simulation, we implemented a tabu search using MATLAB®. The applied tabu search procedure is illustrated in Figure 1. In all cases, the calculation time of the optimization process is less than 700 s in MATLAB 2020b with utilizing Parallel Computing Toolbox™ on the PC with Intel CORE i9-9960X and 128 GB RAM.

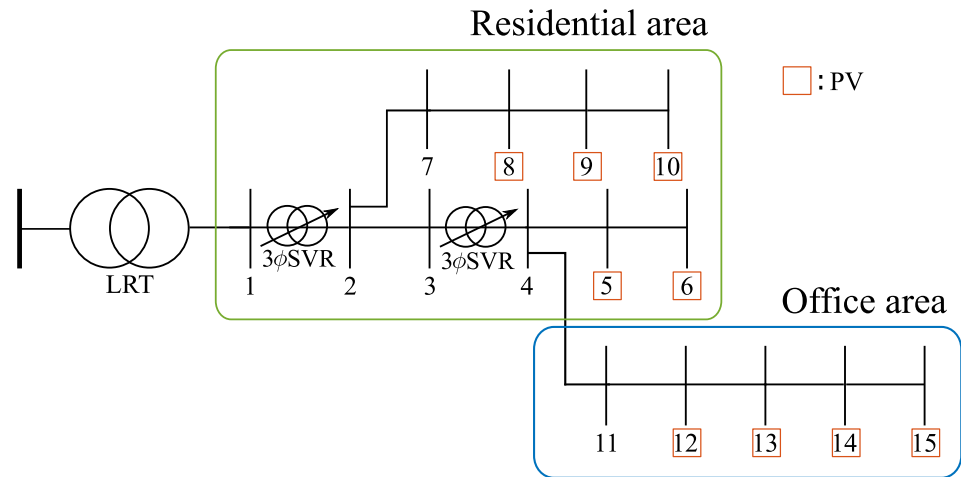


**Figure 1.** Flowchart of the applied tabu search.

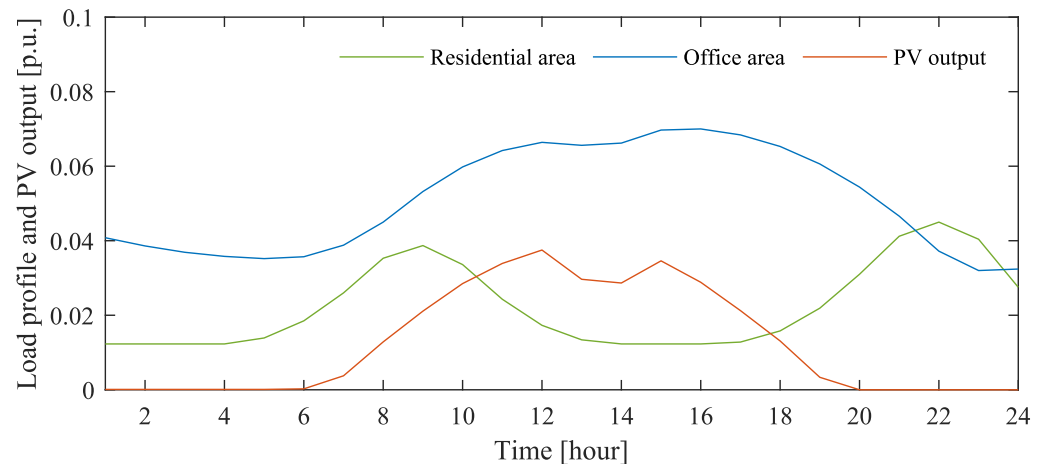
#### 4.2. Distribution System Model

In this study, simulations are performed using a modified version of the MV distribution system model used in [22]. It is shown in Figure 2. The model has residential and

office areas; and the daily load profile of each area and PV output are assumed as Figure 3. The daily load profiles in Figure 3 is extended as three-phase unbalanced loads by decreasing 20% in phase *b* and increasing 20% in phase *c*. PV is installed only in phase *a*.



**Figure 2.** The configuration of the distribution system model; 3 $\phi$ SVRs are installed on line 1–2 and line 3–4.



**Figure 3.** Load profile of each area and PV output; the load profiles is extended as three-phase unbalanced loads by decreasing 20% in phase *b* and increasing 20% in phase *c*. PV is installed only in phase *a*.

#### 4.3. Case Study and Discussion

In this subsection, we discuss the simulation results of a base case and five cases that represent different formulations. The cases presented in this paper are listed below:

- Base case
- Case1: minimize VUF
- Case2: minimize sum of all voltage unbalance metrics
- Case3: minimize losses
- Case4: minimize losses with voltage unbalance penalty
- Case5: minimize losses with voltage unbalance and tap operation penalty

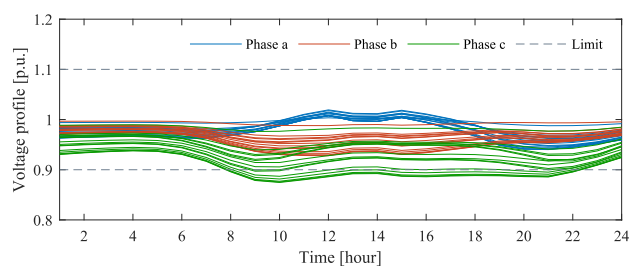
Each of the cases solved each of the five optimization problems presented in Section 3. The optimization problem solutions are compared perspective of three different unbalance metrics, voltage deviations, network losses, and tap operations described in Section 2. In all cases, the voltage deviation rate is limited to  $VD_{lim} = 10\%$ ; in Cases 4 and 5, the voltage unbalance limits are set to  $VUF_{lim} = VUF_{0,lim} = PVUF_{lim} = 2\%$ ; in Case 5, the number of

tap operations per day is limited as  $T_{lim} = 5$ . The results of unbalances, losses, and the number of tap operations for all cases is summarized in Table 1. Figures 4–9 illustrates voltage profile, unbalance metrics, and tap operation for each case.

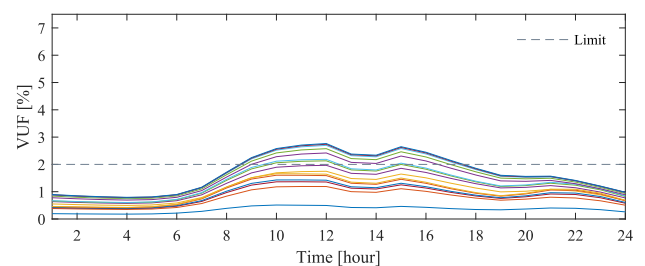
The simulation result for the Base case is shown in Figure 4, where no control devices are installed. In the Base case, there are critical voltage drops in phase *c*, and each unbalance metric during the day is much higher than the limits.

**Table 1.** Simulation results of unbalances, losses, and tap operations for all cases; the smallest values are shown in bold, and overlimit values are shaded.

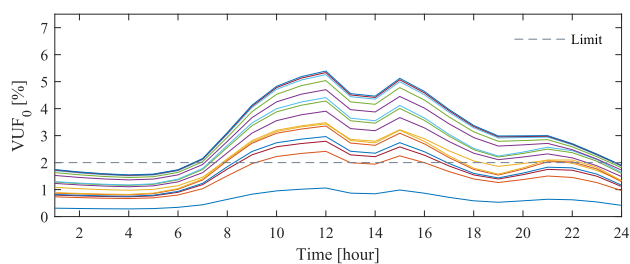
	Base Case	Case 1	Case 2	Case 3	Case 4	Case 5
Max tap count	-	38	39	15	19	<b>5</b>
Total tap count	-	236	169	66	84	<b>23</b>
Max loss (kWh)	422.93	412.31	406.87	<b>328.36</b>	<b>328.36</b>	328.79
Total loss (kWh)	6291	5714	5244	<b>4708</b>	4736	4860
Max VUF (%)	2.7646	<b>0.4575</b>	1.5634	1.7174	1.5847	1.5282
Total VUF	429	<b>70</b>	241	183	199	174
Max VUF <sub>0</sub> (%)	5.3932	2.9344	<b>1.6160</b>	2.2315	1.9095	1.7794
Total VUF <sub>0</sub>	821	423	<b>186</b>	304	264	290
Max PVUR (%)	7.1722	2.8215	<b>1.2713</b>	2.5634	1.7614	1.7868
Total PVUR	1133	405	<b>155</b>	293	252	253



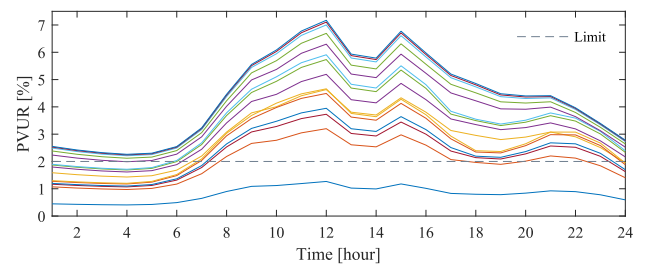
(a) Voltage profile



(b) VUF

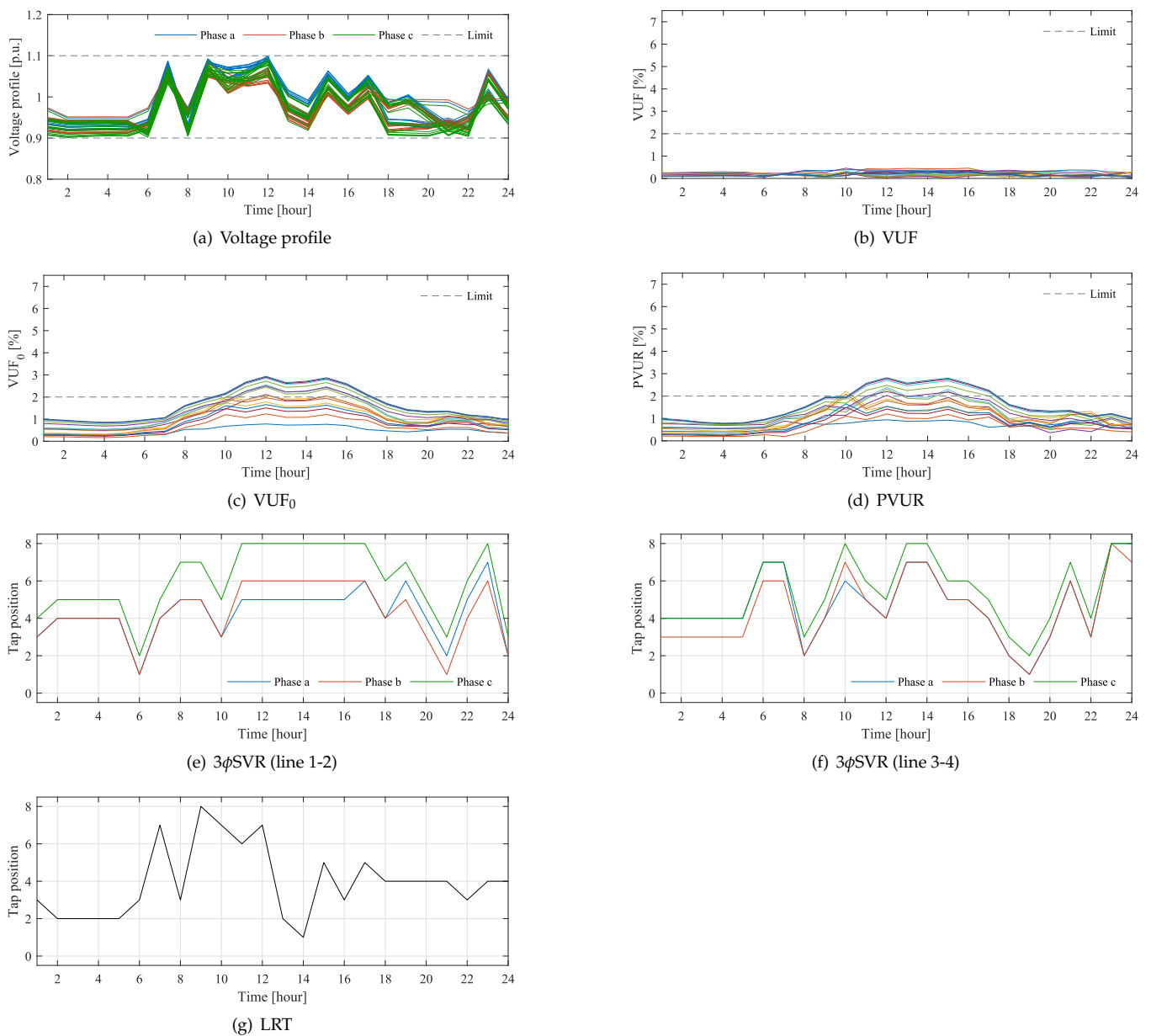


(c) VUF<sub>0</sub>

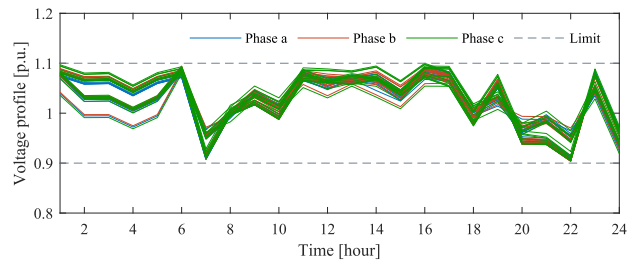


(d) PVUR

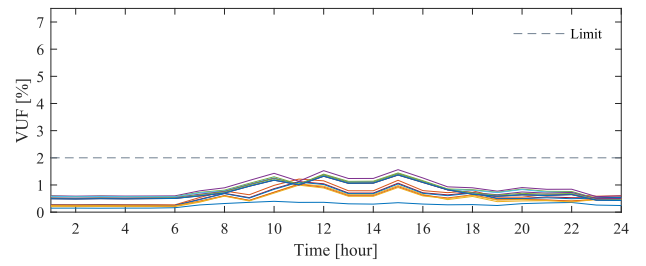
**Figure 4.** Simulation result of Base case; the different colors in (b–d) refer to different buses. There is a critical voltage drop in phase *c*, and each unbalance metric during the day is much higher than the limit.



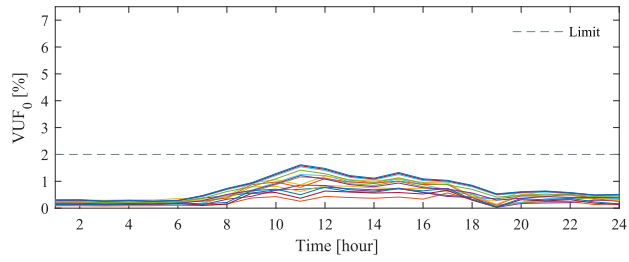
**Figure 5.** Simulation result of Case 1: minimize VUF; the different colors in (b–d) refer to different buses. The VUF satisfies the constraint value for all-day, but the maximum values of VUF<sub>0</sub> and PVUR are above 2%.



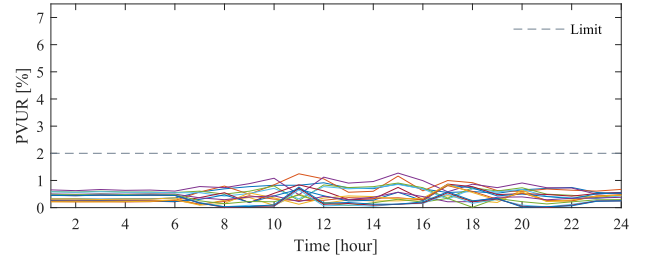
(a) Voltage profile



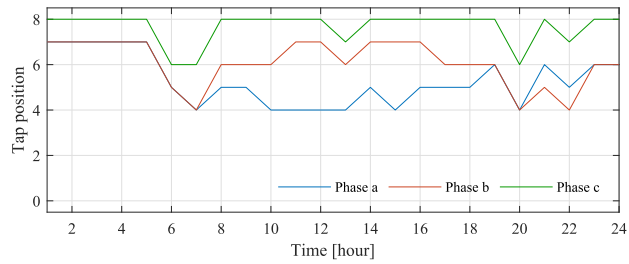
(b) VUF



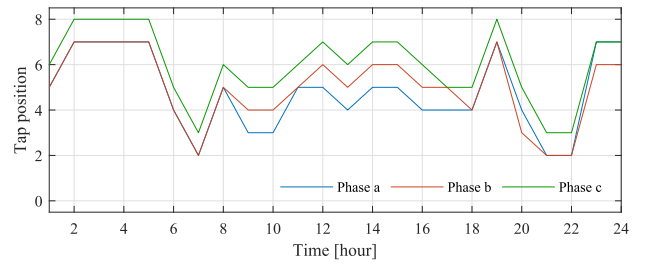
(c) VUF<sub>0</sub>



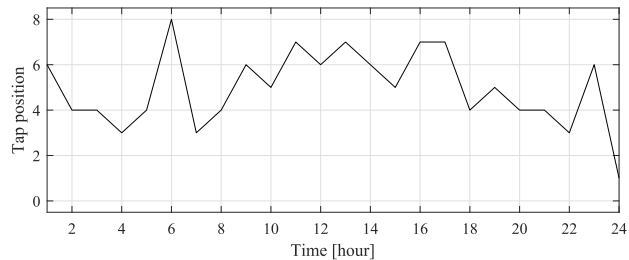
(d) PVUR



(e) 3 $\phi$ SVR (line 1-2)

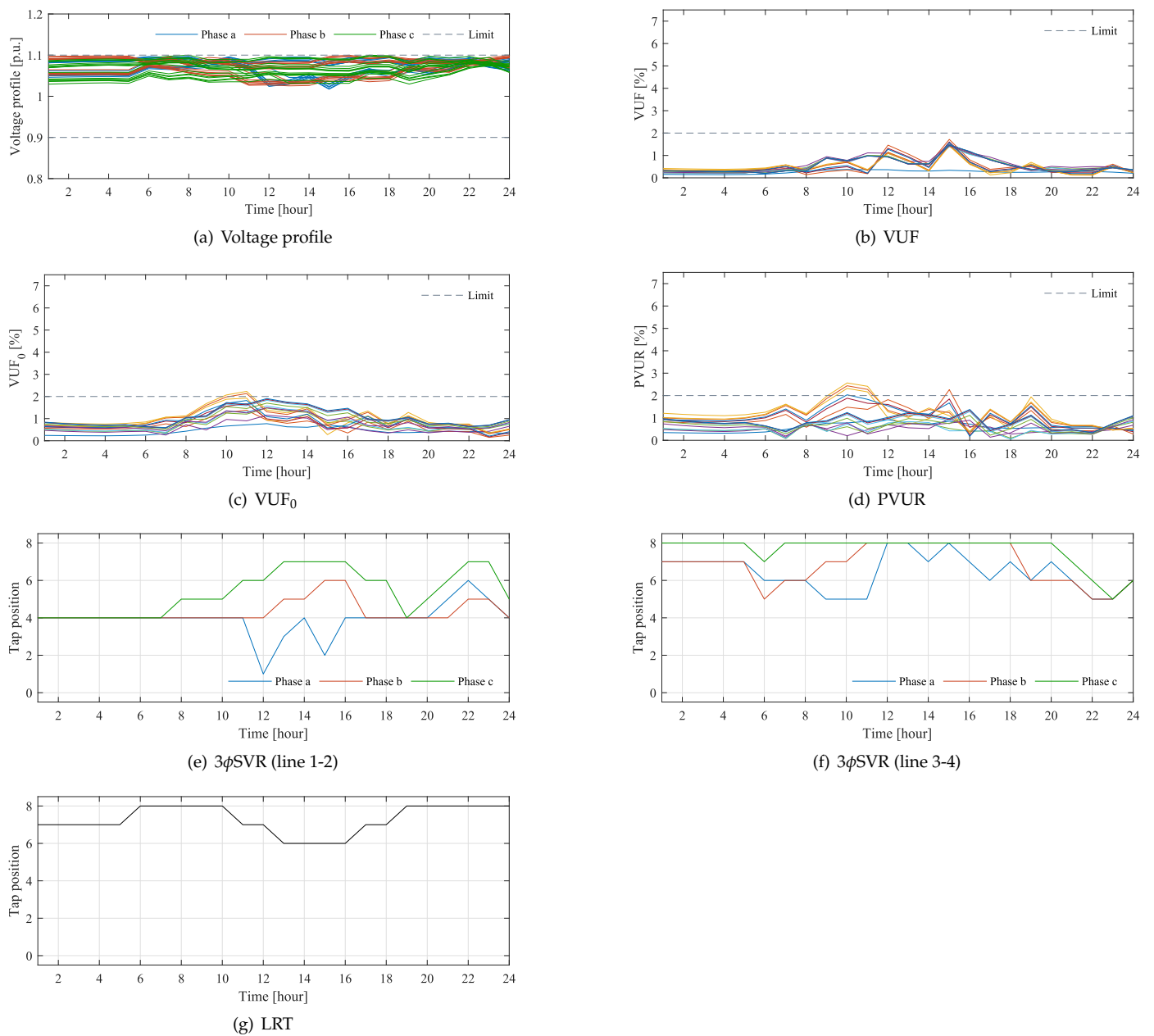


(f) 3 $\phi$ SVR (line 3-4)

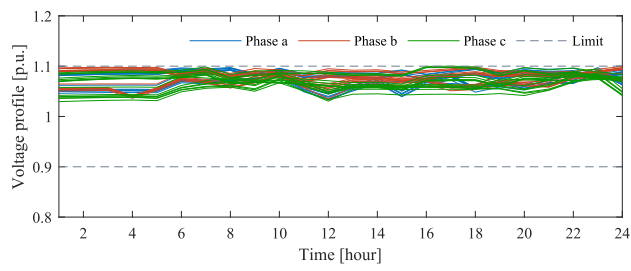


(g) LRT

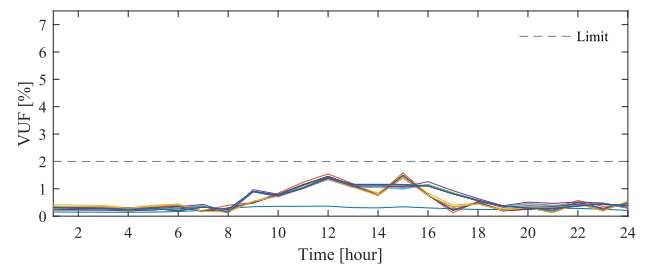
**Figure 6.** Simulation result of Case 2: minimize sum of all voltage unbalance metrics; the different colors in (b–d) refer to different buses. All unbalance metrics are less than 2% for all-day.



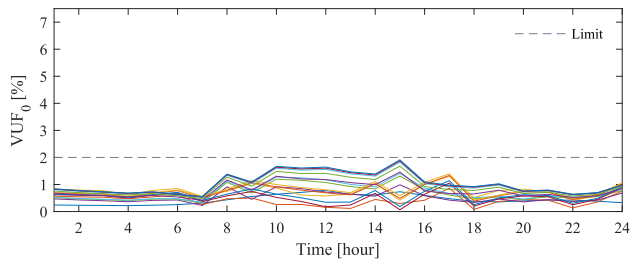
**Figure 7.** Simulation result of Case 3: minimize losses; the different colors in (b–d) refer to different buses. All unbalance metrics considerably improves even though they are not taken into account; VUF is within 2% for all buses, but other metrics exceed 2% for few buses.



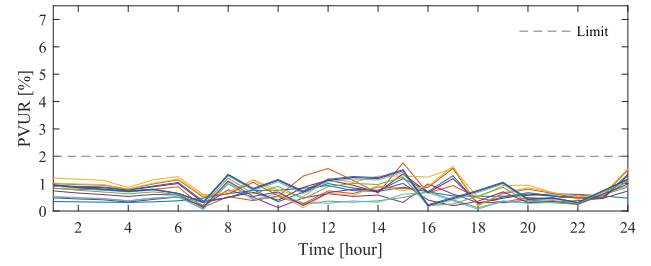
(a) Voltage profile



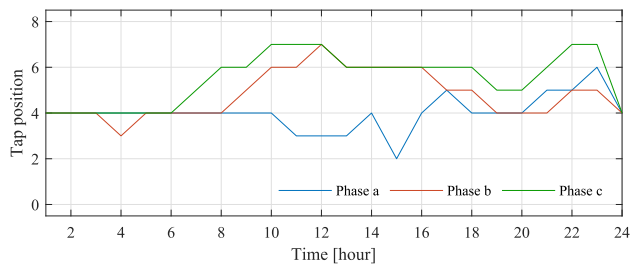
(b) VUF



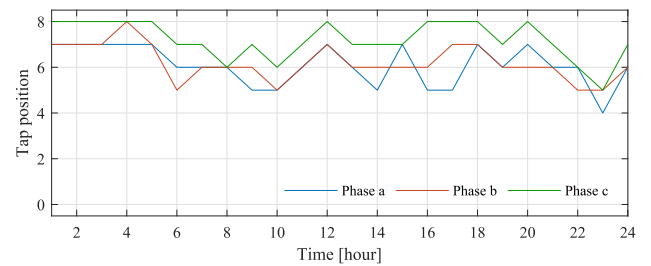
(c) VUF<sub>0</sub>



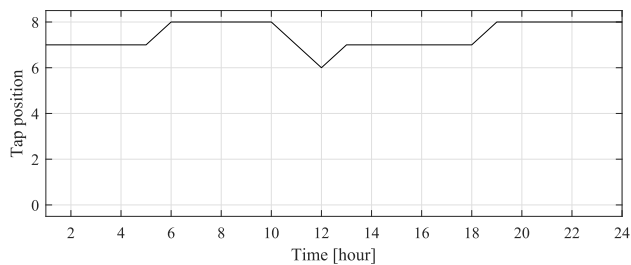
(d) PVUR



(e) 3φSVR (line 1-2)



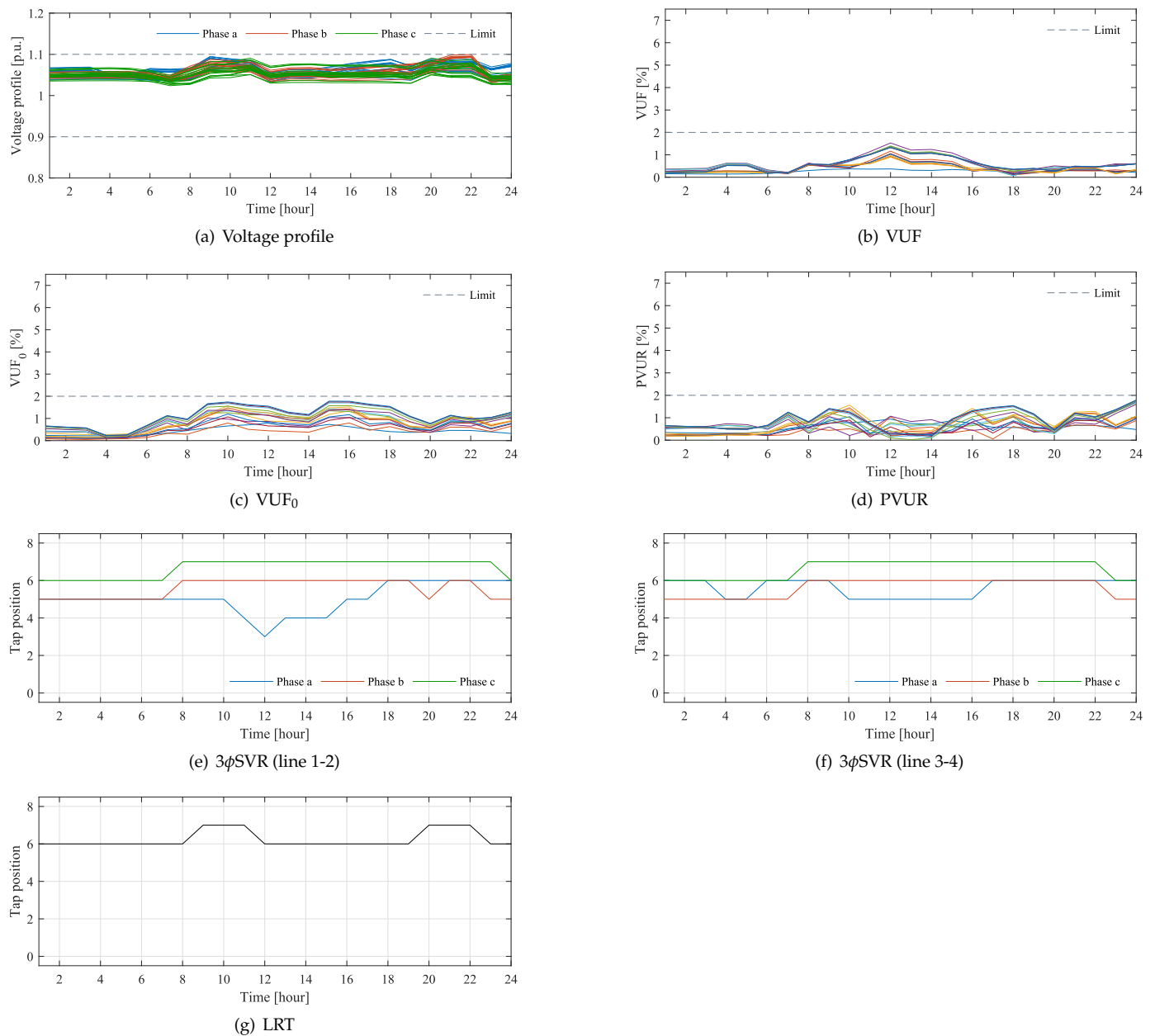
(f) 3φSVR (line 3-4)



(g) LRT

**Figure 8.** Simulation result of Case 4: minimize losses with voltage unbalance penalty; the different colors in (b–d) refer to different buses. Similar to Case 2, all unbalance metrics are less than 2% for all-day.





**Figure 9.** Simulation result of Case 5: minimize losses with voltage unbalance and tap operation penalty; the different colors in (b–d) refer to different buses. All unbalance metrics are less than 2% for all-day while the taps of all devices are operated evenly.

Figure 5 illustrates the solution for Case 1. In this case, the total VUF is minimized, and the VUF satisfies the constraint value for all-day. From Table 1, the VUF of Case 1 is the smallest among the cases in both maximum and total values. Furthermore, no voltage violation occurred. However, we observe that the maximum values of VUF<sub>0</sub> and PVUR are above 2%. This result implies that an optimization considering only specific metrics may violate the other metrics' limits. Figure 6 illustrates the solution for Case 2. This case minimizes the total of VUF, VUF<sub>0</sub>, and PVUR for a day. We observe from Figure 6 and Table 1 that all unbalance metrics are less than 2% for all-day. On the other hand, Case 3 solved the optimization problem with the objective of loss minimization. The solution for Case 3 is shown in Figure 7. Note that unbalance compensation is not considered in Case 3. Table 1 shows that the total loss is the smallest among the cases. From Figure 7, we observe that all unbalance metrics considerably improves even though they are not taken into

account. It seems to have occurred due to the concentration of the voltage of each phase near the upper limit. In addition, VUF is within 2% for all buses, but other metrics exceed 2% for few buses. It shows that loss minimization can significantly reduce the unbalance metrics, but unacceptable unbalance may remain depending on the network conditions. Therefore, the unbalance metrics should be explicitly monitored and incorporated in the optimization problem. In Case 4, the penalty constraint for voltage unbalance was added to the formulation of Case 3. Figure 8 illustrates the solution for Case 4. Figure 8 and Table 1 show that all unbalance metrics are below 2% for all-day, in exchange for a slight increase in losses than Case 3. Compared to Case 2, the total loss in Case 4 improves about 500 kWh, while the maximum values of all unbalance metrics are below 2%. This result shows that voltage unbalance and losses can be improved simultaneously by formulating an appropriate optimization problem. The formulations up to Cases 1–4 do not take into account the improvement of tap operations. Hence, the solutions of Cases 1–4 show the excessive or unbalanced operation of the 3 $\phi$ SVR and LRT taps. For example, in Case 3 and Case 4, only 3 $\phi$ SVR installed on line 3–4 operates intensively in the early morning hours. Moreover, Table 1 shows that the total number of tap operations per day is very high in Cases 1–4. In Case 5, the penalty constraints for the improvement of tap operations were added to the formulation of Case 4. Figure 9 illustrates the solution of Case 5. Similar to Case 4, the maximum values of all unbalance metrics are less than 2% throughout the day. Compared to Case 4, there is a slight increase in losses, but the taps of all devices are operated evenly. In addition, the taps in all phases of devices operate five times or less per day. The results of Case 5 show that introducing 3 $\phi$ SVRs and proper formulation can improve multiple issues such as voltage unbalances, voltage deviations, network losses, and tap operations simultaneously.

## 5. Conclusions

This paper aimed to verify the voltage unbalance compensation by optimal tap operation scheduling of 3 $\phi$ SVRs and LRT. In the formulations of the optimization problems, multiple voltage unbalance metrics as well as network losses, voltage deviations, and cooperative tap operations were considered. In order to investigate the mutual influence between voltage unbalance and these issues, five optimization problems were formulated. The case study showed that minimizing only VUF does not satisfy the VUF<sub>0</sub> and PVUR limits. It implies the need for comprehensive consideration of multiple voltage unbalance metrics. The results obtained when minimizing losses subject to the voltage unbalance constraints showed that it is possible to obtain a low losses solution without violating any voltage unbalance metrics. Furthermore, the results obtained in the final formulation demonstrated that it is possible to significantly improve the network losses and tap operations while satisfying the voltage unbalance and deviation limits. Therefore, we conclude that with an appropriate formulation, 3 $\phi$ SVR and LRT can be properly coordinated to compensate for voltage unbalance while taking other issues into account.

Because this paper focused on the unbalance compensation using 3 $\phi$ SVRs and LRT, active and reactive power supports by distributed energy resources are omitted. However, the integrated control of these will significantly improve voltage unbalances even if more severe unbalanced conditions, and it is our future work in progress.

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